

Geodesy

Geodesy is the study of the size, shape and gravity field of the Earth and Earth's orientation in space.

Some (modern) techniques

- Global Navigation Satellite System (GNSS, includes GPS)
- Interferometric Synthetic Aperture Radar Analysis (space-based, ground-based)
- Electronic Tiltmeters
- Gravity Measurements (space, ground)
- Electronic Distance Measurement (EDM)
- Laser Scanning (LiDAR; terrestrial, aerial)
- Structure from Motion (SfM)

GNSS - Continuous Installations 1/3

short-term continuous:



Picture: R. Grapenthin 4/40

GNSS - Continuous Installations 2/3

very stable:



Picture: UNAVCO 5/40

GNSS - Continuous Installations 3/3





GNSS - Campaign / Episodic Installations 1/5

Benchmark:



GNSS - Campaign / Episodic Installations 2/5

Benchmark:



GNSS - Campaign / Episodic Installations 3/5

Setup (spike mount):

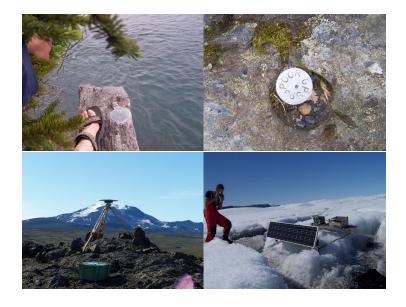


GNSS - Campaign / Episodic Installations 4/5

Setup (tripod):



GNSS - Campaign / Episodic Installations 5/5



GNSS - Campaign Oops

Setup (tripod):

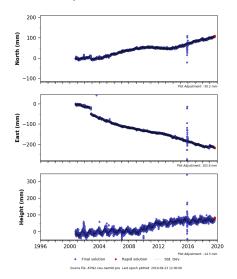


images: R. Grapenthin

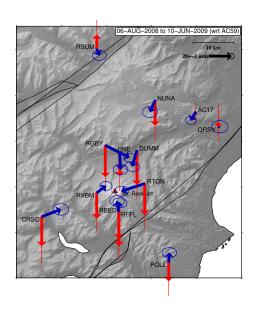
GNSS - Products: time series

ATW2 (ATW2 AKDA AK2000) NAM08

Processed Daily Position Time Series - Cleaned (SD > 20 Removed)



GNSS - Products: Displacement Maps



GNSS - Products: velocity fields

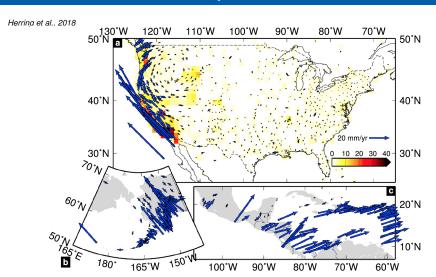
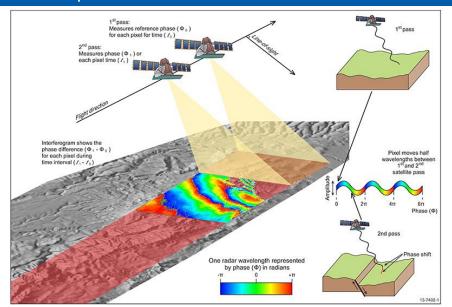
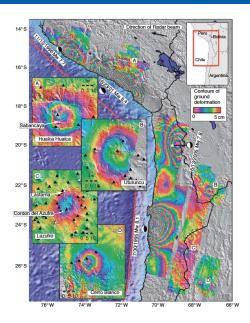


Figure 1. Horizontal velocities from the GAGE solution in (a) the contiguous United States, (b) Alaska, and (c) the Caribbean. The solution is decimated for clarity in Figure 1a, where only approximately 15% of the stations in the solution are shown west of 110°W. Velocity uncertainties are plotted at 95% confidence but are imperceptibly small at this scale. The background color map in Figure 1a shows the station density per square degree of the processed network in the contiguous U.S.

InSAR - space-based



InSAR - Products: Interferograms



InSAR - Products: Time Series

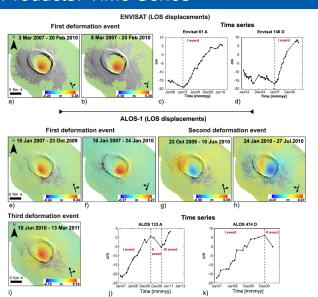


Figure 2. Time series results ENVISAT LOS displacement map (a) for ascending orbit of (March 2007 to February 2010) and (b) for descending orbit 140 (March 2007 to February 2010), (c and d) ENVISAT time series (ts) (see star in Figure 1c for location). ALOS+1 LOS displacement map (e) for ascending orbit 133 (January 2007 to October 2009) and (f) for descending orbit 474 (January 2007 to January 2010). ALOS+1 LOS displacement map (g) for ascending orbit 133 (October 2009) and (b) for descending orbit 474 (January 2010 to July 2010). (ALOS+1 LOS displacement map for ascending orbit 133 (June 2010 to March 2011) () and (b) (LOS+1 time series (see star in Figure 1c for location). In (a), (b), and (e)-(d) data are unwapped, and spatially occlude look-angle errors.

Ground-based SAR 1/2

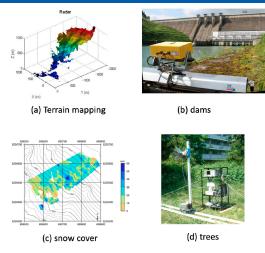


Figure 11. Examples of GBRI applications: (a) terrain mapping, digital elevation model of a slope obtained through GBSAR (after [84]) (b) dams monitoring (courtesy of IDS georadar [48]); (c) snow cover monitoring, map of snow water equivalent change obtained by GBSAR (after [85]); (d) trees monitoring by GBSAR (after [86]).

Ground-based SAR 2/2



Figure 4. Examples of ground-based radar interferometers: (a) no-DOA (after [48]); (b) Rotary (after [49]); (c) linear SAR (after [48]); (d) MIMO (after [50]); (e) ArcSAR (after [48]); (f) moving slot (after [21]).

source: Pieraccini and Miccinesi, 2019, Remote Sensing



















R. Grapenthin



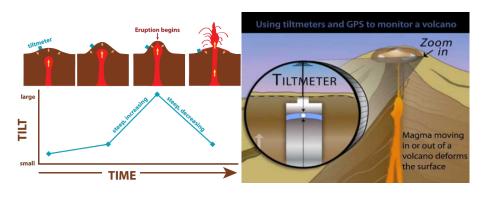


R. Grapenthin





Tiltmeters



Mount St. Helens Science & Learning Center; Iris

Tiltmeters: Products - time series

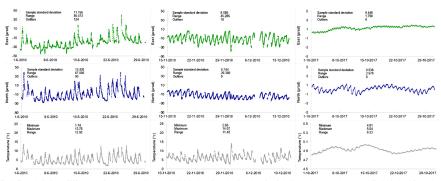
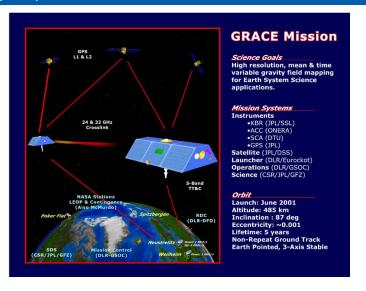


Fig. 8 Time series for tittmeet 95SD, monitoring Sotian viscano (see Apola et al., 2017). Left column: tiltmeet installed at the surface, fixed with expansion screws and epoxy cement (Fig. 7, left column). Center column: tiltmeet installed at the surface, fixed with expansion screws and epoxy cement (Fig. 7, left column). Center column: tiltmeet installed below the surface, fixed with expansion screws. The upper row corresponds to the slope in the Kort component, and the bottom row to temperature.

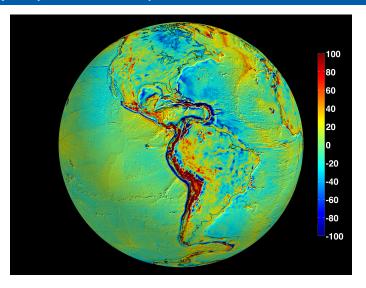
Battaglia et al., 2019

Gravity - space based



courtesy: Geoscience Australia, http://www.ga.gov.au/scientific-topics/positioning-navigation/geodesy/geodetictechniques/interferometric-synthetic-aperture-radar

Gravity - space based: product



courtesy: NASA-JPL

Gravity - ground-based



Fig. 30 Set up of a gravity benchmark at Mount St Helens. Note the drilled leg holes for the Scintrex CG-5 tripod Photo courtesy of M. Poland, US Geological Survey.

Gravity - ground-based: product

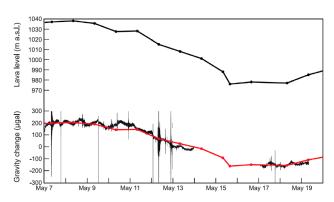


Figure 7. Comparison between lava level (upper plot) and gravity (black curve in lower plot) spanning the May 2015 draining of Kilauea's summit lava lake. Using the model of *Carbone et al.* [2013], a lava density of ~1400 kg/m³ is necessary to fit the gravity change based on the constraints provided by the change in lava level (red curve).

Poland and Carbone, 2016

Electronic Distance Measurement (EDM) 1/4



Electronic Distance Measurement (EDM) 2/4



Fig. 1 Using the EDM in the field: measurement of the baseline between a base station and the target reflector installed on the flank of the volcanic edifice— Puracé Volcano (Colombia) using a total station. A total station is an electronic theodolite integrated with EDM and an on-board computer to collect data and perform calculations.

Electronic Distance Measurement (EDM) 3/4

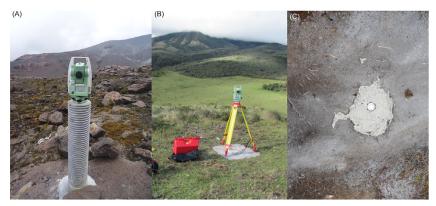
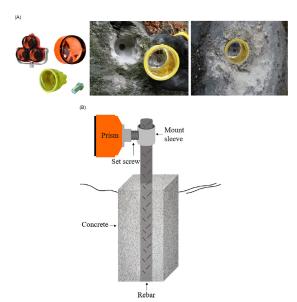


Fig. 2 Different EDM base stations: (A) Concrete column; (B) Concrete baseplate; (C) Small plate or screw in stainless steel.

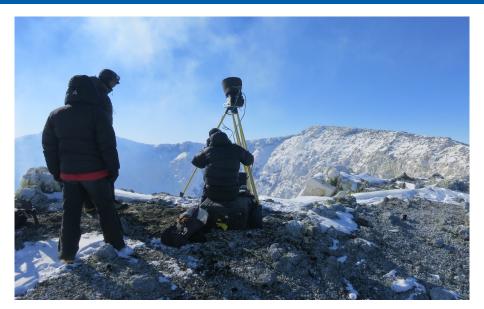
Electronic Distance Measurement (EDM) 4/4



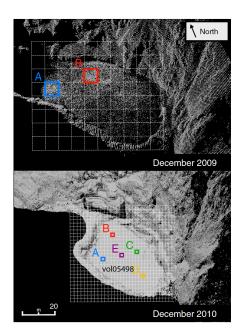
Laser Scanning



Laser Scanning

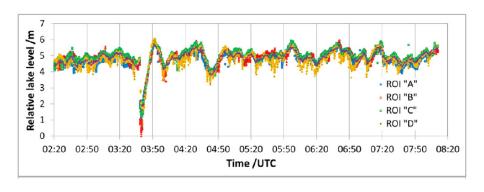


Laser Scanning: Product - point cloud



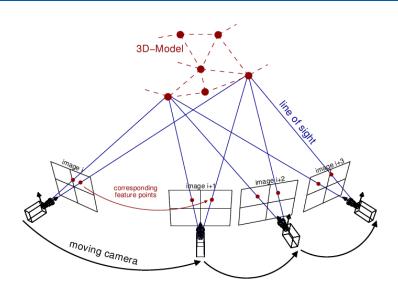
Jones et al., 2015

Laser Scanning: Product - time series



Jones et al., 2015

Structure from Motion



source: Theia.sfm.org 2016

Structure from Motion

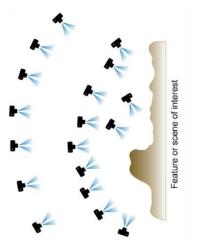


Figure 1: Example of imagery acquisition. Structure from Motion photogrammetry requires multiple photographs with large overlap collected from different positions and directions.

Structure from Motion

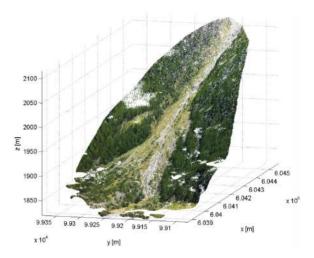
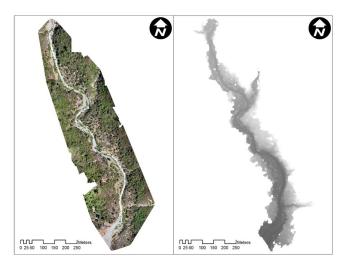


Figure 5: Alluvial fan point cloud generated using smartphone imagery and 123D Catch (Micheletti et al., 2014).

Structure from Motion: Eelriver



source: http://gsp.humboldt.edu/OLM/Courses/GSP_216_Online/lesson8-2/SfM.html