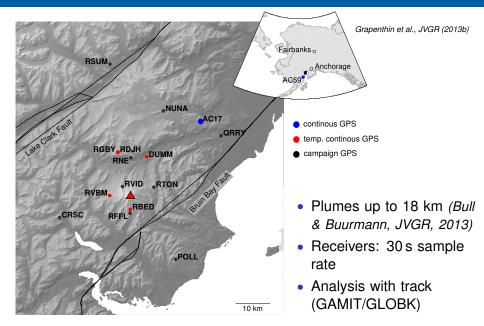


Phase Residuals

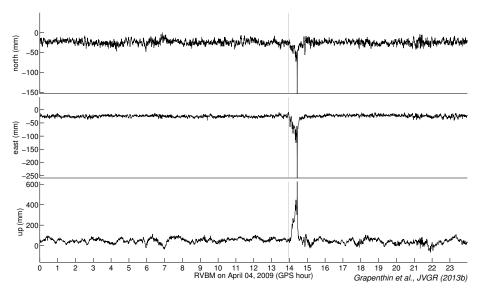
- Generally try to reduce phase residuals as much as possible.
- Are we making any assumptions in the processing?

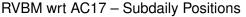
Phase Residuals

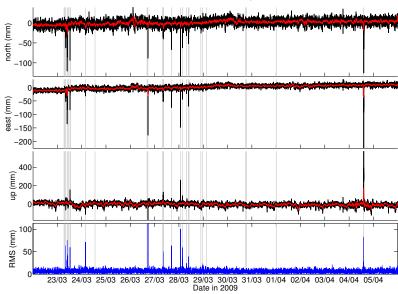
- Generally try to reduce phase residuals as much as possible.
- Are we making any assumptions in the processing?
- YES! Remember all the troposphere, ocean load and other models?
- · Worthwhile to investigate phase residuals for systematic 'signals'!
- Might find new application for GPS!



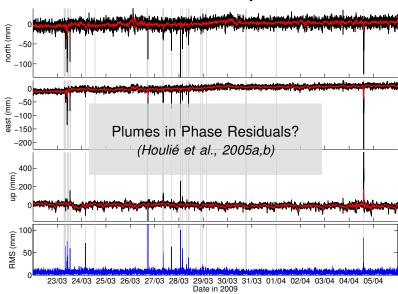
RVBM wrt AC17 - Subdaily Positions

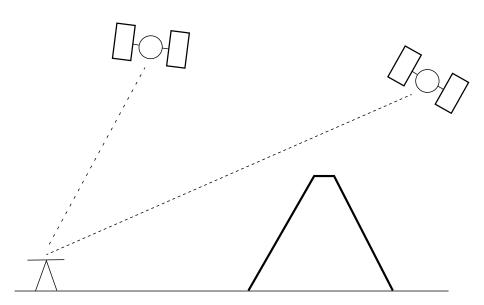


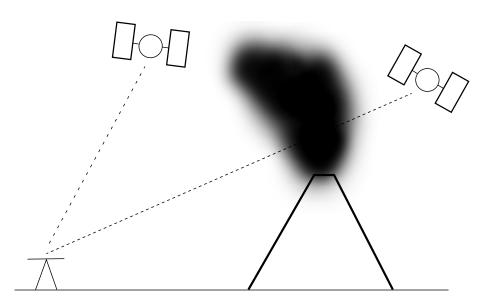


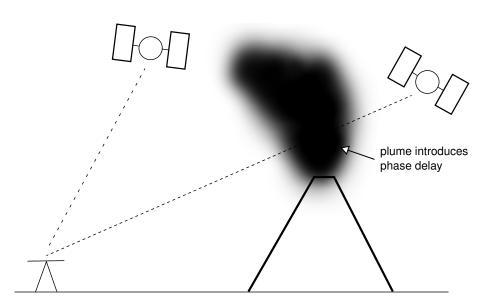


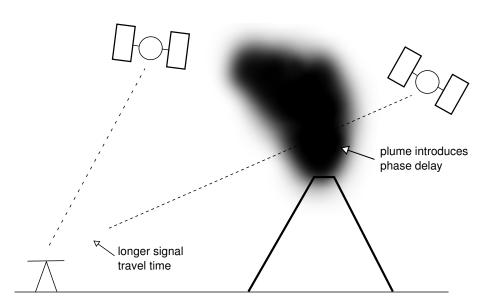


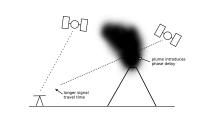


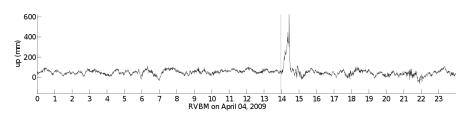


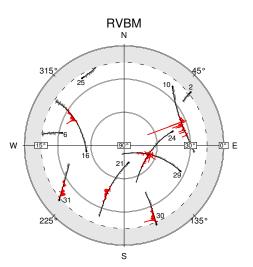






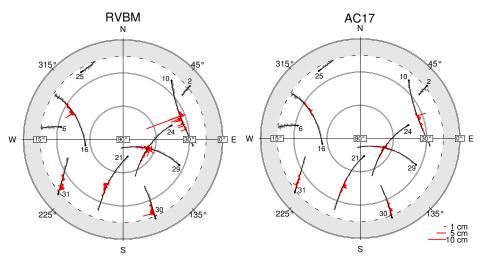






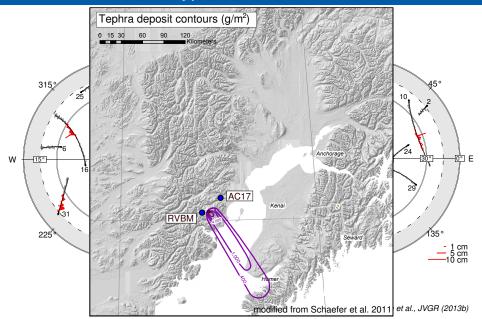
Explosion: 04 April 2009, 14:00 to 14:40 UTC

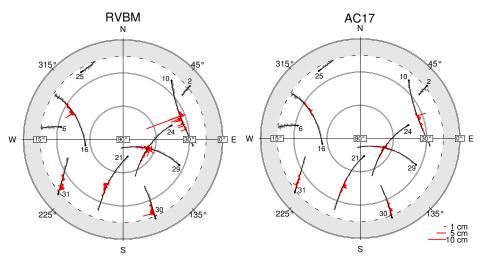
Grapenthin et al., JVGR (2013b)



Explosion: 04 April 2009, 14:00 to 14:40 UTC

Grapenthin et al., JVGR (2013b)



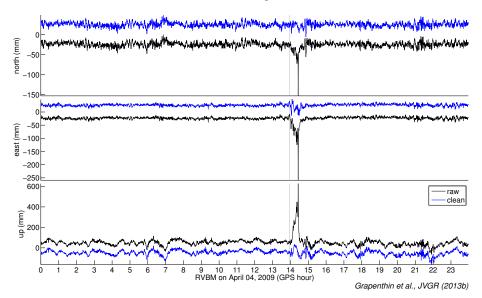


Explosion: 04 April 2009, 14:00 to 14:40 UTC

Grapenthin et al., JVGR (2013b)

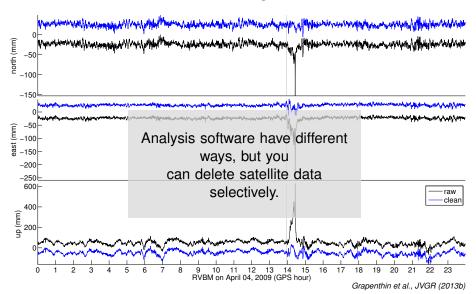
Phase Residuals: Clean up ...

RVBM – AC17

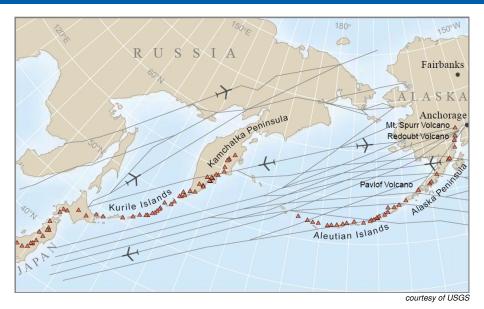


Phase Residuals: Clean up ...

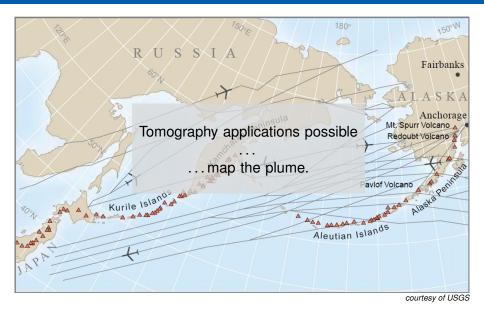




Plumes w/ GPS Why do we care?



Plumes w/ GPS Why do we care?



Plumes: What's with Remote Sensing?

Satellite Repeat Times:

Sensor	Temporal Resolution	Spatial Resolution
AVHRR	1-6 h	1×1 km
MODIS	2×daily	1×1 km
GOES	25 min	TIR: 4-8 km
OMI	2×daily	13×24 km
ASTER	16 days	TIR: 90 m

Webley et al., JVGR (2013)

- direct (A_d) and reflected (A_m) signals interfere – multi-path
- interference effect provides:
 - how wet reflecting surface is
 - distance between reflecting surface and antenna
- High-precision GNSS antennas are designed to suppress multipath
- don't entirely remove it, but
 A_m << A_d (A is SNR
 Amplitude, see below)

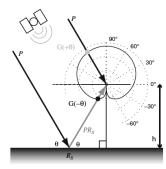
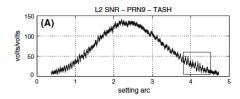


Fig. 2 Geometry of a single ground-bounce multipath signal and effects on signal power, for antena height h and satellite elevation angle θ . Ocnoriti dashed circles indicate power levels of receiving antenna gain pattern G (solid line), while arrows indicate GPS signal patts. For an incoming GPS signal of power P, the direct signal will pierce the gain pattern at an angle equivalent to the satellite elevation angle, so that $A_d = PG(i+\theta)$. A parallel incoming signal will be reflected from the ground and attenuated by a reflectivity factor R_c . Assuming perfect specular reflection, the attenuated, multipathed signal will enter the gain pattern at the negative (below-horizon) satellite elevation angle, so that $A_m = (PR_c) G(-\theta)$. In general, $G(i+\theta) > G(i-\theta)$. Gain pattern pierce points are indicated by large filled circles, with elevation angles marked on the outside right of the properties of the signal pattern and the signal pattern pierce points are indicated by large filled circles, with elevation angles marked on the outside right on the properties of the pr

- new L2 C/A (L2C) (Block IIR-M satellites and above) 20 db-Hz improvement in recorded SNR over old L2 signals
- direct component of SNR must be removed
- MP contribution to SNR is small, but oscillatory
- direct contribution to SNR large in magnitude, but only 1 complete cycle per satellite pass
- depending on application discard data above/below certain elevation angles



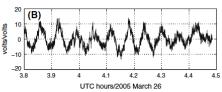


Fig. 3 a L2 SNR data for satellite (PRN) 9 at TASH on 2005 March 26; b SNR data for setting satellite with direct signal contribution removed with a low-order polynomial

Larson et al., 2008, GPS Solutions

- multipath from horizontal, planar reflectors (ground) simple to model
- multipath affects all observations (pseudorange, carrier phase, SNR), focus on SNR!
- SNR independent of orbits, atmospheric delays, clocks!
- MP contribution to GPS SNR (signal to noise ratio):

- multipath from horizontal, planar reflectors (ground) simple to model
- multipath affects all observations (pseudorange, carrier phase, SNR), focus on SNR!
- SNR independent of orbits, atmospheric delays, clocks!
- MP contribution to GPS SNR (signal to noise ratio):

$$SNR = Acos\left(\frac{4\pi h}{\lambda}sin(E) + \phi\right)$$
 $f = \frac{4\pi h}{\lambda}$

- SNR: signal to noise ratio
- f: multipath frequency
- h: antenna height
- λ: GPS signal wavelength

- E: satellite elevation angle
- A: SNR amplitude
- φ: SNR phase offset

- SNR interference pattern related to:
 - snow depth: linearly related to SNR frequency

black

- soil moisture: near surface changes produce small changes in SNR phase offset
- vegetation water content: decreases in SNR amplitudes
- Daily products at http://xenon.colorado.edu/portal.

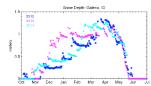
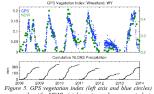


Figure 7. Snow depth measured at GPS site near Galena, Idaho for three water years. For clarity, error bars are not shown, but on average are 4 cm.



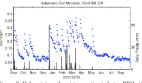
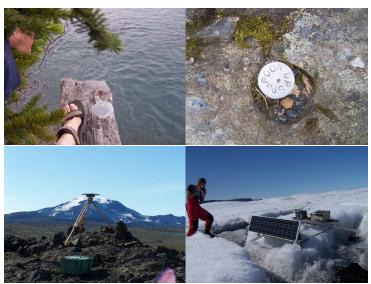


Figure 8. Volumetric soil moisture estimated at a PBO site compared with NDVI (right axis and green circles). in Northern California. Daily precipitation data come from NLDAS. Cumulative precipitation derived from NLDAS is shown in

Larson and Small, 2014, Proc. IGARSS

1) Your own campaigns: periodically go out and occupy benchmarks



2) build continuous sites (\$10+k)





3) data archives

- UNAVCO DAI http://www.unavco.org/data/gps-gnss/data-access-methods/dai2/app/dai2.html
- UNAVCO FTP ftp://data-out.unavco.org/pub/
- SOPAC ftp://garner.ucsd.edu/pub/, http://sopac.ucsd.edu/dataBrowser.shtml
- UNR (products) http://geodesy.unr.edu/billhammond/ gpsnetmap/GPSNetMap.html (have ftp, too)
- regional networks, e.g. BARD: http://seismo.berkeley.edu/bard/

- 3) data archives (continued)
 - Japan GEONET: open, but need to register http:// datahouse1.gsi.go.jp/terras/terras_english.html
 - New Zealand GEONET: ftp://ftp.geonet.org.nz/gps/, 1Hz: ftp: //ftp.geonet.org.nz/rtgps/rinex1Hz/PositioNZ/
 - NSF funded research required to make data available publicly, not all research in US NSF funded, though
 - Other countries may not have open data sharing policy contact potential collaborators!